CONTENTS

	Details of Tables	Page
СНА	PTER 1: UNITS AND MEASURES	1.1 - 1.22
1.1	S.I. Basic quantities and their units	1.1
1.2	S.I. Derived quantities and their units	1.2
1.3	Standard prefixes of S.I. units	1.3
1.4	Some standard quantities in S.I/MKS/CGS/FPS units and their relations $% \mathcal{A} = \mathcal{A} = \mathcal{A} = \mathcal{A}$	1.4
1.5	General physical quantities in mechanical and thermal sciences with $\ensuremath{\mathrm{S.I}}$ units	1.5
1.6	Measures of length	1.8
1.7	Measures of surfaces	1.9
1.8	Measures of volume	1.10
1.9	Metric units of liquid measures	1.10
1.10	Land measuring units	1.10
1.11	Conversion factors for various quantities	1.12
1.12	Conversion factors between SI and FPS units	1.17
1.13	Conversion factors for different measures	1.19
1.14	Conversion factors for SI units	1.20
1.15	Conversion of thermometric scales	1.21
1.16	The greek alphabet	1.21
1.17	Roman and Arabic numerals	1.22
СНА	PTER 2: MATERIALS AND THEIR PROPERTIES	2.1 - 2.53
2.1	Periodic table of materials	2.2
2.2	Physical properties of elements	2.3
2.3	Properties of metallic solids	2.8
2.4	Properties of non-metallic solids	2.10
2.5	Properties of inorganic compounds	2.12

i

2.6	Properties of organic compounds	2.19
2.7	Properties of liquids	2.21
2.8	Properties of gases	2.23
2.9	Mechanical properties of carbon steel castings	2.25
2.10	Mechanical properties of iron castings with spheroidal graphite	2.26
2.11	Mechanical properties of grey cast iron	2.27
2.12	Mechanical properties of high tensile steel castings	2.28
2.13	Mechanical properties of carbon steel forgings	2.28
2.14	Mechanical properties of wrought steels	2.29
2.15	Mechanical properties and applications of cast irons and cast steels	2.30
2.16	Properties and uses of carbon steels	2.32
2.17	Properties and uses of alloy steels	2.34
2.18	Mechanical properties of stainless steels in softened condition	2.37
2.19	Mechanical properties of stainless steels in hardened condition	2.38
2.20	Tensile strength of structural steels	2.38
2.21	Indian standard designation of steel based on chemical composition	2.39
2.22	Indian standard designation of steel based on mechanical properties	2.42
2.23	Effect of alloying elements on steel	2.44
2.24	Properties of brasses	2.46
2.25	Properties of tin bronze	2.46
2.26	Properties of plastics	2.47
2.27	Materials for gears	2.48
2.28	Recommended values of factor of safety	2.49
2.29	Conversion of hardness number	2.49

ii

СНА	PTER 3: FITS, TOLERANCES AND OTHER MANUFACTURING LIMITATIONS	3.1 - 3.30
3.1	Preferred numbers	3.1
3.2	Degree of accuracy expected of manufacturing processes	3.2
3.3	Recommendations for selection of tolerance grades	3.3
3.4	Fundamental tolerances for sizes upto 500 mm	3.4
3.5	Fundamental tolerances for sizes above 500 mm and upto 3150 mm $$	3.5
3.6	Relative magnitude of IT tolerances for sizes upto 500 mm	3.5
3.7	Relative magnitude of IT tolerances for sizes above 500 mm and upto 3150 mm	3.6
3.8	Recommended diameter steps	3.6
3.9	Formulae for fundamental deviations for shafts upto 500 mm	3.8
3.10	Formulae for fundamental deviations for shafts and holes for sizes upto 3150 mm	3.9
3.11	Fundamental deviation values for shafts upto 500 mm	3.10
3.12	Fundamental deviation values for holes upto 500 mm	3.12
3.13	Commonly used types of fits for holes	3.14
3.14	Commonly used types of fits for shafts	3.16
3.15	Types of fits for different applications	3.17
3.16	Tolerance values for holes	3.18
3.17	Tolerance values for shafts	3.19
3.18	Mean fit and variation about the mean fit (Hole basis)	3.22
3.19	Mean fit and variation about the mean fit (Shaft basis)	3.26
3.20	Symbols for surface roughness	3.27
3.21	Surface roughness expected from different manufacturing processes	3.27
3.22	Surface roughness, value grades and symbols	3.28
3.23	Sheet and wire gauge	3.29

СНА	PTER 4: STRESS-STRAIN RELATIONS	4.1 - 4.50
	I. Symbols with S.I. units	4.1
	4.6	
	(i) Simple stresses (Uni-axial stresses)	4.6
	(ii) Uni-axial deformations	4.7
	(iii) Curved beams	4.10
	(iv) Bi-axial stresses	4.11
	(v) Bi-axial deformations	4.12
	(vi) Tri-axial deformations	4.13
	(vii) Theories of failure	4.13
	(viii) Variable simple stresses	4.14
	(ix) Variable combined stresses	4.15
4.1	Properties of commonly used metals	4.18
4.2	Values of factor of safety	4.18
4.3	Poisson's ratio for commonly used materials	4.18
4.4	Coefficient of thermal expansion	4.19
4.5	Circumference, area, volume for different objects	4.19
4.6	Properties of various cross-sections	4.23
4.7	Shear, bending moment and deflections for beams	4.25
4.8	Values of radius of curvature in curved beams	4.29
4.9	Stress concentration factor for stepped shaft in tension	4.47
4.10	Stress concentration factor for stepped shaft in bending	4.47
4.11	Stress concentration factor for stepped shaft in torsion	4.48
4.12	Stress concentration factor for grooved shaft in tension	4.48
4.13	Stress concentration factor for grooved shaft in bending	4.49
4.14	Stress concentration factor for grooved shaft in torsion	4.49
4.15	Stress concentration factor for a plate with hole in tension	4.50

4.16 Stress concentration factor for a shaft with transverse hole in bending	4.50
CHAPTER 5: SHAFTS	5.1 - 5.18
I. Symbols with S.I. units	5.1
II. Design particulars and equations	5.6
(i) Diameter of solid shaft for steady loads	5.6
(ii) Diameters of hollow shaft for steady loads	5.7
(iii) Diameter of solid shaft for variable loading	5.10
(a) Soderberg equation for simple loading	5.10
(b) Soderberg equation for combined loading	5.11
(iv) Critical speeds of shafts	5.15
(v) Deflections on shafts due to various loading conditions	5.16
5.1 Shock and fatigue factors	5.14
5.2 Properties of shafting materials	5.17
5.3 Meximum permissible working stresses for shafts	5.18
5.4 Column factor	5.18
5.5 Standard diameter of shafts	5.18
CHAPTER 6: KEYS AND PINS	6.1 - 6.27
I. Symbols with S.I units	6.1
II. Design particulars and equations	6.1
6.1 Cross-section of parallel, tapered and gib-head keys	6.8
6.2 Dimensions of parallel keys and key ways	6.9
6.3 Gib-head keys and key ways	6.10
6.4 Taper keys and key ways	6.12
6.5 Dimensions of woodruff keys	6.14
6.6 Dimensions of woodruff key ways	6.15
6.7 Relationship of shaft diameter to woodruff key size	6.17
6.8 Straight side splines	6.18
6.9 Dimensions for cylindrical pins	6.21
6.10 Preferred length, diameter for cylindrical pins	6.22

v

6.11	Dim	ensions for taper pins	6.24
6.12	Dim	ensions for splined shaft	6.27
6.13	Allo	wable compressive stress for keys	6.27
CHA	APTE	R 7: COUPLINGS	7.1 - 7.14
	I.	Symbols with S.I units	7.1
	II.	Design particulars and equations	7.2
		(i) Muff coupling	7.2
		(ii) Split muff coupling	7.3
		(iii) Rigid flange coupling	7.4
		(iv) Flexible flange coupling	7.6
7.1	Dime	ensions for rigid couplings (Forged end)	7.8
7.2	Dime	ensions for flexible couplings (Bush type)	7.10
7.3	Dime	ensions for flexible couplings (Disc type)	7.11
7.4	Servi	ce factors	7.12
7.5	Char	acteristics of flexible couplings	7.14
CHA	APTE	R 8: COTTER AND KNUCKLE JOINTS	8.1 - 8.8
	I. Sy	mbols with S.I. units	8.1
	II. D	esign particulars and equations	8.3
	(i)	Socket and spigot cotter joint	8.3
	(ii) Sleeve and cotter joint	8.5
	(ii	i) Gib and cotter joint	8.7
	(iv	y) Knuckle joint	8.7
CHA	APTE	R 9: THREADED FASTENERS AND SCREWED JOINTS	9.1 - 9.24
	I.	Symbols with S.I units	9.1
	II.	Design particulars and equations	9.4
		(i) Fluid tight joint	9.4
		(ii) Adjustable screw joint (Turn buckle)	9.5

vi

	(iii) Eccentric loaded bolted joints	9.7
	(a) Load parallel to axis of bolt	9.7
	(b) Load perpendicular to axis of bolt	9.8
	(c) Load in the plane containing the bolts	9.9
9.1	Properties of some bolt materials	9.13
9.2	Strength of screw fasteners	9.13
9.3	Ratio of elasticity for screw joints	9.14
9.4	Working stress for metric coarse thread	9.14
9.5	Coarse and fine threads	9.15
9.6	Dimensions for metric screw threads	9.16
9.7	Proportions of hexagonal head bolt and nut	9.23
CHA	PTER 10: RIVETED JOINTS	10.1 - 10.24
	I. Symbols with S.I. units	10.1
	II. Design particulars and equations	10.4
	(i) Boiler and structural joints	10.4
	(ii) Diamond joint (Lozenge joint)	10.9
	(iii) Eccentric riveted joint	10.10
10.1	Length of general purpose rivets (for $d \leq 10 \ mm)$	10.13
10.2	Length of general purpose rivets (for $d = 12$ to 48 mm)	10.14
10.3	Length of boiler rivets	10.17
10.4	Type of riveted joints	10.19
10.5	Standard sizes of rivets	10.19
10.6		10.00
10.0	Longitudinal joints for pressure vessels	10.20
10.0	Longitudinal joints for pressure vessels Boiler code factor	10.20 10.20

vii

10.10	10 Diamond joint 10.23			
10.11	11 Working stress at elevated temperatures			10.23
10.12	Allo	owable	stress for structural joints	10.24
CHA	PTE	R 11:	WELDED JOINTS	11.1 - 11.18
	I.	Sym	bols with S.I. units	11.1
	II.	Desi	gn particulars and equations	11.3
		(i) S	trength of fillet weld for tensile load	11.3
		(ii) S	Strength of eccentrically loaded fillet welds	11.6
		(iii)	Welded joints for fatigue loading	11.9
11.1	Ma	ster cł	nart of welding processes	11.13
11.2	Des	sign st	resses for welded joints	11.14
11.3	Stress concentration factors for welded joints 11.15			
11.4	4 Minimum size of fillet welds 11.15			
11.5	Pro	perties	s of welding electrodes	11.15
11.6	Allo	owable	loads for fillet welds	11.16
11.7	Allo	owable	loads for butt welds	11.16
11.8	Pro	perties	s of section of welds	11.17
CHA	РТЕ	R 12:	PRESSURE CYLINDERS	12.1 - 12.11
	I.	Symb	bols with S.I. units	12.1
	II.	Desig	gn particulars and equations	12.3
		(i)	Thin cylinders	12.3
		(ii)	Thin spherical shell	12.4
		(iii)	Thick cylinders (single)	12.4
		(iv)	Thick cylinders (compound)	12.8
		(v)	Cylinder head cover plates	12.9
12.1	Plat	e thic	kness of boiler	12.11
12.2	Woi	king s	stress at elevated temperatures	12.11

12.3	Percentage error when thick cylinder is treated as thin cylinder	12.11
СНА	PTER 13: PIPES AND PIEP JOINTS	13.1 - 13.7
	I. Symbols with S.I. units	13.1
	II. Design particulars and equations	13.3
	(i) Pipes	13.3
	(ii) Circular flanged pipe joint	13.4
	(iii) Oval flanged pipe joint	13.6
13.1	Thickness allowance for pipes	13.7
13.2	Allowable tensile stresses for pipes	13.7
13.3	Working stress at elevated temperatures	13.7
СНА	PTER 14: SPRINGS	14.1 - 14.28
	I. Symbols with S.I units	14.1
	II. Design particulars and equations	14.7
	(i) Helical springs subjected to static loading	14.7
	(ii) Concentric springs	14.13
	(iii) Helical springs subjected to variable loading	14.14
	(iv) Helical torsion spring	14.20
	(v) Flat spiral spring	14.21
	(vi) Leaf springs	14.22
	(vii) Disc springs	14.27
14.1	Spring design stresses	14.15
14.2	Mechanical properties of helical spring materials	14.16
14.3	Relative parameters of helical spring ends	14.17
14.4	Values of buckling factor	14.17
14.5	SWG numbers for helical spring wires	14.18

ix

14.6	Standard wire sizes for helical springs	14.19
14.7	Mechanical properties of leaf spring materials	14.24
14.8	Standard sizes of leaf springs	14.24
14.9	Proportions for leaf springs	14.25
14.10	Standard sections of laminated springs	14.26
CHA	PTER 15: LEVERS	15.1 - 15.11
	I. Symbols with S.I. units	15.1
	II. Design particulars and equations	15.5
	(i) Hand and foot levers	15.5
	(ii) Cranked levers	15.7
	(iii) Bell-crank levers	15.8
	(iv) Rocker arm	15.10
СНА	PTER 16: I.C. ENGINE CYLINDERS AND PISTONS	16.1 - 16.12
	I. Symbols with S.I. units	16.1
	II. Design particulars and equations	16.4
	(i) Engine cylinders	16.4
	(ii) Pistons	16.6
16.1	Proportions for piston, rings and piston pin	16.10
16.2	Recommended piston speed	16.12
16.3	Stroke-bore ratio	16.12
16.4	Thickness of piston head	16.12
CHA	PTER 17: PISTON ROD, PUSH ROD AND CONNECTING ROD	17.1 - 17.12
	I. Symbols with S.I. units	17.1
	II. Design particulars and equations	17.4

х

17.1	Characteristics of columns	17.8
17.2	Rankine's constant 'a'	17.9
17.3	Parameters of columns	17.9
17.4	Connecting rod materials	17.9
17.5	Proportions of connecting rod	17.11
17.6	Values of inertia factor	17.12
СНА	PTER 18: CRANKSHAFT	18.1 - 18.6
	I. Symbols with S.I units	18.1
	II. Design particulars and equations	18.3
	(i) Overhung crankshaft	18.3
	(ii) Centre crank shaft	18.3
СНА	PTER 19: FLYWHEEL	19.1 - 19.8
	I. Symbols with S.I. units	19.1
	II. Design particulars and equations	19.3
19.1	Coefficient of fluctuation of speed	19.6
19.2	Coefficient of fluctuation of energy	19.6
19.3	Fluctuation of energy for steam engine	19.8
СНА	PTER 20: HYDRO DYNAMIC JOURNAL BEARINGS	20.1 - 20.26
	I. Symbols with S.I. units	20.1
	II. Design particulars and equations	20.3
20.1	Journal bearing materials and applications	20.8
20.2	Recommended speeds of machineries	20.10
20.3	Product of pressure and velocity	20.11
20.4	Specific gravity at 15°C	20.12

xi

20.5 Design values for journal bearings	20.13
20.6 Diametral clearances	20.15
20.7 Dimensionless parameters for full journal bearing	20.16
20.8 Dimensionless parameters for 180° bearing	20.18
20.9 Dimensionless parameters for 120° bearing	20.20
20.10 Dimensionless parameters for 60° bearing	20.22
20.11 Absolute viscosity of lubricating oils	20.26
CHAPTER 21: BALL AND ROLLER BEARINGS	21.1 - 21.34
I. Symbols with S.I units	21.1
II. Design particulars and equations	21.2
21.1 Applications of ball and roller bearings	21.5
21.2 Life of bearings	21.6
21.3 Service factor	21.7
21.4 Load Carrying capacity at high temperatures	21.7
21.5 Equivalent bearing load	21.8
21.6(a) Loading ratio for ball bearings	21.9
21.6(b) Loading ratio for roller bearings	21.10
21.7(a) Deep groove ball bearings (Series 60)	21.13
21.7(b) Deep groove ball bearings (Series 62)	21.14
21.7(c) Deep groove ball bearings (Series 63)	21.16
21.7(d) Deep groove ball bearings (Series 64)	21.18
21.8(a) Self-aligning ball bearings (Series 22)	21.19
21.8(b) Self-aligning ball bearings (Series 23)	21.20
21.9(a) Single row angular contact ball bearing (Series 72 B)	21.21
21.9(b) Single row angular contact ball bearing (Series 73 B)	21.22
21.10 Double row angular contact ball bearings (Series 33A)	21.23

xii

21.11	Single thrust ball bearings (Series 512)	21.24	
21.12	Double thrust ball bearings (Series 522)	21.26	
21.13(a) Cylindrical roller bearings (Series NU22)	21.27	
21.13(b) Cylindrical roller bearings (Series NU23)	21.28	
21.14	Taper roller bearings (Series 322)	21.29	
21.15	Spherical roller bearings (Series 222C)	21.30	
21.16	Needle bearings (Series NA49)	21.32	
21.17	Geometric relations	21.33	
21.18	Characteristics of bearings	21.34	
CHAP	TER 22: POWER TRANSMISSION SYSTEMS - BASICS	22.1 - 22.4	
I.	Symbols with S.I. units	22.1	
I	. Design particulars and equations	22.2	
22.1 T	ypes and applications of power transmission systems	22.2	
22.2 N	lechanisms of mechanical power transmission	22.3	
22.3 E	fficiency of power transmission elements	22.3	
22.4 C	haracteristics of mechanical drives	22.4	
CHAP	TER 23: FLAT BELT DRIVES	23.1 - 23.12	
	I. Symbols with S.I. units	23.1	
	II. Design particulars and equations	23.2	
23.1	Arc of contact and length	23.4	
23.2	Characteristics of flat belts	23.5	
23.3	Allowable tensions per mm width of belt	23.5	
23.4	Coefficient of friction	23.6	
23.5	Nominal belt width	23.6	
23.6	Load correction factor 23.7		
23.7	Arc of contact factor	23.7	
23.8	Minimum pulley diameters	23.7	

xiii

23.9	Rating for fabric belts	23.8
23.10	Specifications of transmission belting	23.8
23.11	Pulley width related to belt width	23.9
23.12	Standard widths of pulleys	23.9
23.13	Nominal diameters of pulleys	23.9
23.14	Thickness of belts	23.9
23.15	Crown of flat pulleys	23.10
CHAF	PTER 24: V-BELT DRIVES	24.1 - 24.16
	I. Symbols with S.I units	24.1
	II. Design particulars and equations	24.2
24.1	Types of V-belts and dimensions	24.3
24.2	Correction factors for service	24.3
24.3	Arc of contact factors	24.5
24.4	Pitch length factors	24.6
24.5	Power transmitting capacity	24.8
24.6	Ratings for A type belt	24.9
24.7	Ratings for B type belt	24.10
24.8	Ratings for C type belt	24.11
24.9	Ratings for D type belt	24.12
24.10	Ratings for E type belt	24.13
24.11	Centre distance values	24.14
24.12	Dimensions of V-grooved pulleys	24.15
CHAF	PTER 25: CHAIN DRIVES	25.1 - 25.15
	I. Symbols with S.I. units	25.1
	II. Design particulars and equations	25.3
25.1	Service factor	25.5
25.2	Transmission ratio	25.6

xiv

25.3 Minimum centre distance	25.6
25.4 Factor of safety	25.6
25.5 Allowable bearing stress	25.6
25.6 Coefficient for sag	25.6
25.7 Relationship between centre distance and length of chain	25.7
25.8 Value of m	25.8
25.9 Specifications of chains	25.9
25.10 Transverse pitch	25.15
CHAPTER 26: FIBRE ROPE DRIVES	26.1 - 26.4
I. Symbols with S.I. units	26.1
II. Design particulars and equations	26.2
26.1 Breaking loads and linear density	26.3
CHAPTER 27: WIRE ROPES	27.1 - 27.12
CHAPTER 27: WIRE ROPES I. Symbols with S.I units	27.1 – 27.12 27.1
I. Symbols with S.I units	27.1
I. Symbols with S.I unitsII. Design particulars and equations	27.1 27.3
I. Symbols with S.I unitsII. Design particulars and equations27.1 General properties of ropes	27.1 27.3 27.5
 I. Symbols with S.I units II. Design particulars and equations 27.1 General properties of ropes 27.2 Number of switching on operations for cranes 	27.1 27.3 27.5 27.5
 I. Symbols with S.I units II. Design particulars and equations 27.1 General properties of ropes 27.2 Number of switching on operations for cranes 27.3 Ratio of pulley diameter to wire diameter 	 27.1 27.3 27.5 27.5 27.6
 I. Symbols with S.I units II. Design particulars and equations 27.1 General properties of ropes 27.2 Number of switching on operations for cranes 27.3 Ratio of pulley diameter to wire diameter 27.4 Life and applications of cranes and hoists 	 27.1 27.3 27.5 27.5 27.6 27.6
 I. Symbols with S.I units II. Design particulars and equations 27.1 General properties of ropes 27.2 Number of switching on operations for cranes 27.3 Ratio of pulley diameter to wire diameter 27.4 Life and applications of cranes and hoists 27.5 Specifications of 6 × 7 wire ropes 	 27.1 27.3 27.5 27.5 27.6 27.6 27.6 27.7
 I. Symbols with S.I units II. Design particulars and equations 27.1 General properties of ropes 27.2 Number of switching on operations for cranes 27.3 Ratio of pulley diameter to wire diameter 27.4 Life and applications of cranes and hoists 27.5 Specifications of 6 × 7 wire ropes 27.6 Specifications of 6 × 19 wire ropes 	 27.1 27.3 27.5 27.5 27.6 27.6 27.6 27.7 27.8

xv

CHAPTE	R 28: SPUR AND HELICAL GEAR DRIVES	28.1 - 28.39
	I. Symbols with S.I. units	28.1
	II. Design particulars and equations	28.5
	(a) As per Hertz and Belayev equations	
	(i) Spur gears	28.5
	(ii) Helical and herring bone gears	28.8
	(b) As per Lewis and Buckingham equations	
	(i) Spur gears	28.32
	(ii) Helical gears	28.34
28.1	Materials for gear application	28.11
28.2	Physical properties of metals	28.12
28.3	Mechanical properties of gear materials	28.13
28.4	Grey iron castings for general use	28.13
28.5	Combinations of materials for pinion and wheel	28.14
28.6	Design stress for gear materials	28.15
28.7	Design formulas for cylindrical gears	28.16
28.8	Design twisting moment	28.17
28.9	Load concentration factor	28.17
28.10	Dynamic load factor	28.18
28.11	Equivalent Youngs modulus	28.19
28.12(a)	Face width to centre distance ratio $\left(\psi\right)$	28.19
28.12(b)	Recommended ψ values	28.20
28.13	Face width to module ratio $(\boldsymbol{\psi}_m)$	28.20
28.14	Standard gear ratio	28.20
28.15	Form factor	28.21
28.16	Recommended series of module	28.22
28.17	Peripheral speeds of gears	28.22

28.18	Backlash for gears	28.23
28.19	Design compressive stress	28.23
28.20	Equivalent mean life	28.24
28.21	Life factor for compressive strength	28.25
28.22	Design bending stress	28.25
28.23	Endurance limit stress	28.26
28.24	Factor of safety	28.26
28.25	Stress concentration factor	28.26
28.26	Life factor for bending	28.27
28.27	Design bending stress for non-metallic materials	28.27
28.28	Formulae for plastic deformation	28.28
28.29	Basic dimensions for cylindrical gears	28.29
28.30	Properties of involute teeth	28.30
28.31	Standard tooth proportions	28.30
28.32	Recommended series of diametral pitches	28.31
28.33	Minimum number of teeth on the pinion to avoid interference	28.31
28.34	Allowable static stress (or) Design bending stress	28.36
28.35	Form factor as per Lewis equation	28.36
28.36	Service factor	28.37
28.37	Dynamic factor	28.37
28.38	Expected error in tooth profiles	28.38
28.39	Values of surface endurance limit (σ_e)	28.38
28.40	Comparison of single mesh gears	28.39
CHAPTH	ER 29: BEVEL GEAR DRIVES	29.1 - 29.12
I.	Symbols with S.I. units	29.1
II.	Design particulars and equations	29.4

xvii

		(a) As per Hertz and Belayev equations straight bevel gears	29.4
		(b) As per Lewis and Buckingham equations straight level equations	29.11
29.1	Desi	gn formulas for conical gears	29.7
29.2	Cone	e distance to face width ratio (ψ_y)	29.8
29.3	Perij	pheral speeds of gears	29.9
29.4	Reco	mmended backlash for straight bevel gears	29.10
СНА	PTE	R 30: WORM GEAR DRIVES	30.1 - 30.12
	I.	Symbols with S.I. units	30.1
	II.	Design particulars and equations	30.3
		(a) Gear design as per Hertz and Belayev equations	30.3
		(b) Gear design as per Lewis and Buckingham equations	30.11
30.1	Bas	ic dimensions of worm gear pair	30.7
30.2	Des	ign surface stress	30.8
30.3	Des	ign bending stress	30.8
30.4	Lea	d angle	30.8
30.5	Nur	nber of teeth for worm wheel	30.9
30.6	Effi	ciencies of worm gear drive	30.9
30.7	For	n factor as per Lewis equation	30.12
30.8	Wea	r factor for worm gears	30.12
СНА	PTE	R 31: MULTI-SPEED GEAR BOX	31.1 - 31.14
	I.	Symbols with S.I. units	31.1
	II.	Design particulars and equations (As per Hertz and Belayev equations)	31.3
31.1	Step	s of speeds	31.4

31.2 Number of teeth for pinion and gear for gear box design	31.8
CHAPTER 32: CAM DRIVES 32.1	
I. Symbols with S.I. units	32.1
II. Design particulars and equations	32.3
32.1 Characteristic equations for cam curves	32.5
32.2 Displacement ratio	32.6
32.3 Cam factor	32.7
32.4 Allowable stress for cam materials	32.7
CHAPTER 33: CLUTCHES	33.1 - 33.14
I. Symbols with S.I. units	33.1
II. Design particulars and equations	33.5
(i) Disc clutch	33.5
(ii) Cone clutch	33.7
(iii) Centrifugal clutch	33.7
(iv) Claw clutch	33.8
33.1 Friction materials for clutches	33.11
33.2 Factor for driving system, k_1	33.12
33.3 Factor for driven system, k_2	33.12
33.4 Factor for speed, k_3	33.12
33.5 Factor for engagement, k_4	33.12
33.6 Values of p_b and μ	33.13

СНА	PTER 34: BRAKES	34.1 - 34.16
	I. Symbols with S.I. units	34.1
	II. Design particulars and equations	34.5
	(i) Block brakes	34.5
	(ii) Band brakes	34.8
	(iii) Band and block brakes	34.9
	(iv) Internal expanding shoe brakes	34.11
34.1	Properties of brake lining materials	34.14
34.2	Dimensions of brake-drum	34.14
34.3	Safe bearing pressures for band brakes	34.15
34.4	Width and thickness of band (i.e., Sizes of band)	34.15
34.5	Capacity of brakes	34.15
34.6	Heat radiating factors for brakes	34.16
СНА	PTER 35: POWER SCREWS	35.1 - 35.23
	I. Symbols with S.I units	35.1
	II. Design particulars and equations	35.3
	(i) Screw jack	35.3
35.1	Working stress for metric coarse thread	35.7
35.2	Safe bearing pressures for power screws	35.7
35.3	Allowable bearing pressures for power screw materials	35.8
35.4	Coefficient of friction for power-screws	35.8
35.5	Coefficient of friction as per material combination	35.8
35.6	Coefficient of friction on thrust collar	35.8
35.7	Dimensions for square threads – fine series	35.9

хх

35.835.12Dimensions for square threads - normal series 35.9 35.15Dimensions for square threads - coarse series 35.10 Sizes of nut threads - fine series 35.18 35.19 35.11 Sizes of bolt threads - fine series 35.20 35.12 Sizes of nut threads - coarse series 35.22 35.13 Sizes of bolt threads - coarse series **CHAPTER 36: RATCHET AND PAWL MECHANISM** 36.1 - 36.4 I. Symbols with S.I. units 36.1II. Design particulars and equations 36.236.1 Number of ratchet teeth 36.436.2 Design unit pressure 36.4**CHAPTER 37: GENEVA MECHANISM** 37.1 - 37.4 I. Symbols with S.I. units 37.1II. Design particulars and equations 37.3 **CHAPTER 38: PRESS TOOLS** 38.1 - 38.10 Symbols with S.I. units I. 38.1II. Design particulars and equations 38.2(i) Blanking 38.2(ii) Piercing 38.2(iii) Bending 38.6 38.9 (iv) Drawing 38.1 Radial clearance 38.438.2 Strength of materials 38.4

CHA	PTE	R 39: FINITE ELEMENT TECHNIQUES	39.1 - 39.32
	I. Sy	39.1	
	II. Design particulars and equations		
	(i)	39.3	
	(ii)	One dimensional (Vector variable) problems	39.4
		(a) Bar elements	39.4
		(b) Truss element	39.5
		(c) Beam element	39.5
		(d) Frame element	39.6
	(iii)	Two dimensional (Scalar variable) problems	39.8
	(iv)	Two dimensional (Vector variable) problems	39.10
	(v)	Axisymmetric problems	39.13
	(vi)	Isoparametric elements	39.16
	(vii)	Integration by Gauss-quadrature method	39.20
	(viii)	Three dimensional (Scalar variable) problems	39.21
	(ix)	Three dimensional (Vector variable) problems	39.23
	(x)	Dynamic problems	39.26
	(xi)	Heat transfer problems	39.27
	(xii)	Fluid flow problems	39.32
39.1	Gaus	s points and weights	39.20
СПА	DTFI	R 40: STANDARD MATHEMATICAL FUNCTIONS	40.1 - 40.27
40.1	Alge		40.1
	1.1	Laws of exponents	40.1
	1.2	Ratio and proportions	40.1
	1.3	Arithmetic progression	40.2
	1.4	Geometric progression	40.2
	1.5	Harmonic progression	40.2

	1.6	Sums of numbers	40.3
	1.7	Quadratic equations	40.3
	1.8	Permutations	40.3
	1.9	Combinations	40.4
	1.10	Binomial theorem	40.4
	1.11	Properties of binomial coefficients	40.5
	1.12	Binomial expansions and factors	40.5
	1.13	Binomial series	40.6
	1.14	Logarithms	40.6
	1.15	Exponential and logarithmic series	40.6
40.2	Analy	tical Geometry	40.7
	2.1	Straight line	40.7
	2.2	Circle	40.8
	2.3	Parabola	40.9
	2.4	Ellipse	40.10
	2.5	Hyperbola	40.10
	2.6	Rectangular hyperbola	40.11
40.3	Mens	uration	40.11
	3.1	Plane figures	40.11
	3.2	Solids	40.12
40.4	Trigo	nometry	40.12
	4.1	Trigonometrical Functions	40.13
	4.2	Values for trigonometric functions of some angles	40.14
	4.3	Signs and variations of trigonometric functions	40.14
	4.4	Addition formulae	40.15
	4.5	Multiple angle formulae	40.15

xxiii

	4.6	Sum, difference and product formulae	40.15	
	4.7	Half angle formulae	40.16	
	4.8	Inverse trigonometrical functions	40.16	
	4.9	Relations between inverse trigonometric functions	40.16	
	4.10	Trigonometric series	40.17	
	4.11	Solution of triangles	40.17	
	4.12	Hyperbolic functions	40.18	
	4.13	Hyperbolic series	40.19	
	4.14	Inverse hyperbolic functions	40.19	
40.5	40.5 Calculus		40.19	
	5.1	Differentiation	40.19	
	5.2	Partial differentiation	40.21	
	5.3	Integration	40.21	
40.6	Centi	ntres of gravity		
40.7	Mass	moments of inertia	40.26	
REFE	REFERENCE BOOKS			

INDEX

I.1 - I.14